

P2 — GNSS Sensor Positioning



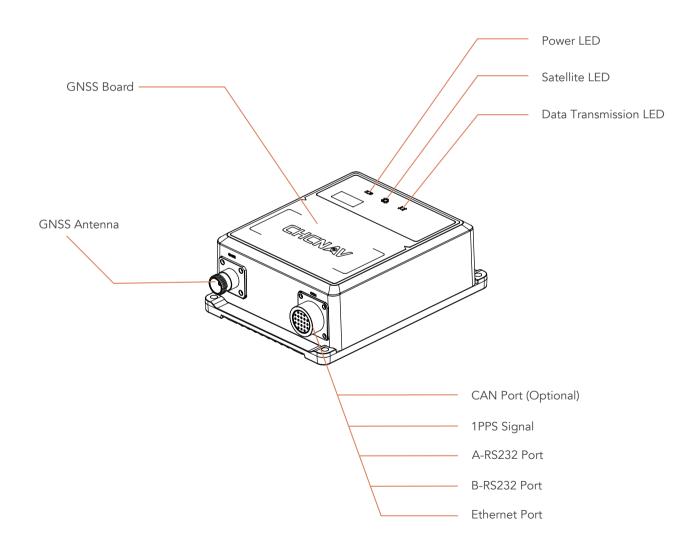
Hardware Description

P2
GNSS Sensor

The P2 GNSS sensor is a multi-channel high-precision receiver designed to provide robust centimeter level positioning to static or dynamic applications.

Integrating the latest GNSS technology in an extremely rugged IP67 and lightweight enclosure, the P2 GNSS sensor is built to withstand harsh environment and ensure extended performances. Easy to install, its configuration web interface allows seamless integration process to system integrators.

The CHCNAV's P2 GNSS sensor is the perfect choice for various range of precision applications: GNSS reference station, marine, industrial automation, robotics...



Key Features

All GNSS Constellations

Advanced and field-proven 336-channel GNSS positioning technology supporting all current and upcoming GNSS signals.



Easy to Install

Connect to the P2 GNSS sensor via industry standard ethernet port and get full control to its configuration via a standard web interface. Virtually no learning curve for faster integration process.



Industrial Design

Integrated industrial-grade power management circuit to provide reliable and constant performances in difficult construction machine environment.



Extended Connectivity

Rich hardware interfaces make the integration seamless in all applications: serial ports, CAN Bus protocol (optional), RJ45 ethernet connectivity and low latency PPS output.



Applications







Specifications

GNSS Characteristics(1)			
Channels GPS	336		
	L1 C/A, L2E, L2C, L5		
GLONASS	L1 C/A, L2 C/A, L3 CDMA		
Galileo	E1, E5A, E5B, E5AltBOC, E6		
BeiDou	B1I, B1C, B2I, B2C, B3I		
SBAS	L1 C/A, L5		
QZSS	L1 C/A, L1 SAIF, L2C, L5, LEX		
IRNSS	L5		
MSS L-Band	OmniSTAR®, Trimble RTX TM		
GNSS Accuracies ⁽²⁾			
Real time	Horizontal: 8 mm + 1 ppm RMS		
kinematic (RTK)	Vertical: 15 mm + 1 ppm RMS		
	Initialisation time: typically < 8 s		
	Initialisation reliability: > 99.9%		
Autonomous	Horizontal: 1.0 m RMS		
	Vertical: 1.5 m RMS		
SBAS	Horizontal: 0.50 m RMS		
	Vertical: 0.85 m RMS		
Code differential	Horizontal: 0.25 m + 1 ppm RMS		
	Vertical: 0.50 m + 1 ppm RMS		
Time to first fix(3)	Cold start: < 45 s		
	Worm start: < 30 s		
	Signal re-acquisition: < 2 s		
Hardware			
Size (L × W × H)	162 mm x 120 mm x 53 mm		
3126 (L ~ ** ~ 11)	(6.4 in x 4.7 in x 2.1 in)		
Weight	(0.4 iii x 4.7 iii x 2.1 iii) ≤ 1.0 kg (35.3 oz)		
Environment	Operating: -40 °C to +75 °C (-40 °F to +167 °F		
FIIAII OIIIII GIIC	Storage: -55 °C to +85 °C (-67 °F to +185 °F)		
Humidity	100%		
Ingress protection	IP67 waterproof and dustproof		
Shock	Survive a 1.2m drop in hard ground		
Certifications			
CE: FCC Part 15 (cla	CE; FCC Part 15 (class B Device), MIL-STD-810G, Method 514.7		

	Communications	
1 x Ethernet port	Network protocols supported > HTTP/HTTPs (WebUI) > NTP Server > NMEA, GSOF, CMR etc over TCP/IP or UDP > NTripCaster, NTripServer, NTripClient	
2 x RS232 ports	Up to 460,800 bps	
1 x 1PPS	3.3V TTL level positive slope pulse 8ms pulse wide and 20ns latency	
Control software	HTML web browser, Internet Explorer, Firefox, Safari, Opera, Google Chrome	
Web user interface	Allows remote configuration, data retrieval and firmware updates, setup of multiple streaming/monitoring ports	
Data Formats		
Reference outputs/inputs	CMR, CMR+, sCMRx, RTCM 2.x, RTCM 3.x	
Navigation outputs	ASCII: NMEA-0183 Binary: Trimble GSOF	
Observation output	RT17, RT27	
Maximum position update rate	50 Hz output standard	
Electrical		
Power consumption	2.7 W (depending on user settings)	
External power input	9 V DC to 36 V DC	

*Specifications are subject to change without notice.

- (1) Subject to availability of BDS ICD and Galileo commercial service definition. B1C will be supported by V5.37 or higher firmware and B2A is optional. GLONASS L3 and Galileo E6 will be provided through future firmware upgrade.
- (2) Accuracy and reliability are determined under open sky, free of multipaths, optimal GNSS geometry and atmospheric condition. Performances assume minimum of 5 satellites, follow up of recommended general GPS practices.
- (3) Typical observed values.



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