# CHCNAV

# **i85**

# COMPACT EFFICIENT POCKET-SIZED LASER IMU-RTK



**SURVEYING & ENGINEERING** 

# EXTREME GNSS PERFORMANCE LASER & CAMERA POWER ON TOP

The i85 Laser IMU GNSS combines cutting-edge technology in a lightweight 800 g design built for daily fieldwork. Powered by a 1408-channel GNSS chip and CHCNAV's iStar2.0 engine, it delivers reliable RTK performance even in harsh conditions—thanks to advanced ionospheric modeling for high fix integrity under intense solar activity.

With AUTO-IMU, there's no need for manual centering—just pick it up and measure. The built-in laser module enables fast, accurate 3D point coordinate capture in obstructed, hard-to-reach, or unsafe areas. Enhanced by high computing power SoC and next-gen IMU, the i85 brings new efficiency to photogrammetric surveys. Up to 21 hours of battery life, plus integrated AR navigation and stakeout, help slash operator workload—no matter their experience level.

# WORLD'S GNSS SALES CHAMPION

#### Trusted quality, lasting precision

The i85 features an upgraded IMU system that enhances heading accuracy, ensuring laser measurement precision of 2 cm at 5 m and 3 cm at 10 m\*. Powered by CHCNAV's full-constellation, full-frequency GNSS chip and proprietary StellaFusion™ 4.0 technology, it delivers consistent, high-precision positioning even in complex environments. Its new-generation laser system adopts an all-in-one design with a reinforced metal frame to maintain sensor alignment and minimize installation errors. Optimized multi-sensor synchronization significantly reduces latency, improving overall computational accuracy. Built for reliability, the i85 also features a temperature sensor that automatically adjusts measurement algorithms, while intelligent gain control adapts to changes in surface lighting and signal quality—ensuring precise, dependable laser measurements wherever the job takes you.

#### **SMART AUTO-FOCUS**

Aim and measure instantly

Powered by an embedded high-performance processor, the i85 performs real-time local image processing, ensuring high-quality visuals with ultra-low latency. It intelligently adjusts zoom and focus based on user behavior, and after just a few seconds of aiming, the system automatically assists in capturing data. No more fumbling with manual operation—what you need is handled for you, seamlessly and effortlessly.

#### **BRIGHT GREEN LASER**

Never lose your target

The i85 features an industrial-grade green laser that delivers exceptional reflectivity across a wide range of surfaces. With resistance to ambient light levels up to 50,000 lux—equivalent to direct midday sunlight—the laser point remains vividly visible, like the morning star against the bright sky.

#### **CLEAR LONG-RANGE SHOTS**

No more hazy targets

The i85 debuts the industry's first true 8MP HD camera, effectively equipping the receiver with a high-definition telescope. Even when zooming in, distant targets remain crisp and sharply defined—say goodbye to blurry, foggy video feeds. Distance is no longer a barrier to precision aiming—bring your target into clear view and measure exactly what you intend to.

## LASER MEASUREMENT WITH EXTENDED RANGE

Over 50% boost in data collection efficiency

In environments where traditional GNSS receivers fail—such as beneath dense canopies or beside high-rise buildings—the i85 overcomes signal challenges with an advanced GNSS + laser ranging hybrid solution. By integrating a high-precision, industry-grade laser module, it enables accurate coordinate acquisition even in obstructed or hard-to-reach areas, boosting overall efficiency by up to 50%. Whether it's across rivers, behind fences, or through restricted zones, the laser easily bypasses physical barriers, saving you from time-consuming detours. Data collection that nonce took three minutes can now be completed in under 30 seconds. And with remote, non-contact laser measurement, users can safely gather data from hazardous areas without ever stepping into danger. With the i85, obstacles vanish, efficiency accelerates, and safety stays by your side.







#### LASER SURVEY

Accurate measurement of previously inaccessible points, Premium laser detector for survey-grade 3D coordinates, Bright green laser and autofocusing for easier aiming.



## EXTREME GNSS PERFORMANCE

CHCNAV iStar2.0, Hybrid GNSS Engine and StellaFusion™ 4.0, 1408-channel and integrated SoC, 96% reliable fix rate, 20% data quality improved.



## VISUAL NAVIGATION AND STAKEOUT

Deep fusion of GNSS, IMU, and Visual, Advanced 1.5 GHz CPU, Adaptive 5.8 GHz Wi-Fi, Unique VPT™ (Virtual Pole Tip) technology.



**AUTO-IMU** 

200 Hz AUTO-IMU eliminates manual initialization, Automatic pole tilt compensation, 3 cm accuracy over a 60° tilt range, Saves up to 30% of time.

### SPECIFICATIONS

GNSS Performance (1)		Hardware	
Channels	1408 channels with iStar2.0	Size (LxWxH)	Φ133 mm x 85 mm (Φ 5.24 in ×
GPS	L1C/A, L2C, L2P(Y), L5		3.35 in)
GLONASS	L1, L2, L3*	Weight	800 g (1.76 lb)
Galileo	E1, E5a, E5b, E6*	Front panel	4 LED, 2 physical buttons
BeiDou QZSS	B1I, B2I, B3I, B1C, B2a, B2b* L1C/A, L1C, L2C, L5	Tilt sensor	Calibration-free IMU for pole-tilt compensation. Immune to magnetic disturbances.
NavIC/ IRNSS	L5	Laser sensor	Class 3R, Green (8)
SBAS	L1, L5*		Cameras
	ccuracies (2)	Sensor pixels	Dual-camera, global shutter with 2 MF
	H: 8 mm + 1 ppm RMS V: 15 mm + 1 ppm RMS	Field of view	& 8 MP. 91°
Real time kinematic (RTK)	Initialization time: <10 s Initialization reliability: >99.9%	Video frame rate	30fps <sup>(9)</sup>
Post-processing kinematic (PPK)	H: 3 mm + 1 ppm RMS V: 5 mm + 1 ppm RMS	Features	LandStar software, support Visual Navigation, CAR AR Visual Stakeout, Laser Survey.
PPP	Support B2b-PPP, E6B-HAS H: 10 cm   V: 20 cm	Communication	
High-precision static	H: 2.5 mm + 0.1 ppm RMS	Wireless connection	NFC for device touch pairing
Static and rapid static	V: 3.5 mm + 0.4 ppm RMS H : 2.5 mm + 0.5 ppm RMS	Wi-Fi	802.11 b/g/n/ac, 5.8 GHz & 2.4 GHz, access point mode
· ·	V : 5 mm + 0.5 ppm RMS	Bluetooth®	v 4.2, backward compatible
Code differential	H: 0.4 m RMS   V: 0.8 m RMS	Ports data dow	1 x USB Type-C port (external power,
Autonomous	H: 1.5 m RMS   V: 2.5 m RMS		data download, firmware update) 1 x UHF antenna port (SMA male)
Visual stakeout <sup>(3)</sup>	H: 8 mm + 1 ppm RMS V: 15 mm + 1 ppm RMS 2 cm within range 5 m	Standard Internal Tx/Rx: 410 - 470 MH Transmit Power: 0.5 W, 1 W	
Laser survey	3 cm within range 10m	Built-in UHF radio Satel Link rate: 9600 bp Range: Typical 3 optimal conditions	Protocol: CHC, Transparent, TT450,
Positioning rate <sup>(4)</sup>	1 Hz, 5 Hz and 10 Hz		Link rate: 9600 bps to 19200 bps
Time to first fix (5)	Cold start: < 45 s Hot start: < 10 s Signal re-acquisition: < 1 s		Range: Typical 3 km, up to 8 km with optimal conditions  RTCM 2.x, RTCM 3.x, CMR input
IMU update rate	200 Hz, AUTO-IMU		output
Till angle	0-60° Additional horizontal pole-tilt	Data formats	HCN, RINEX 2.11, 3.02 NMEA 0183 output NTRIP Client, NTRIP Caster
RTK tilt-compensated	uncertainty typically less than 8 mm + 0.7 mm/° tilt down to 30°	Data storage	8 GB high-speed memory
Envir	ronments	Compliance with	h Laws and Regulations
Temperature	Operating: -40°C to +65°C (-40°F to +149°F) Storage: -40°C to +85°C (-40°F to +185°F)	International standards	IEC 62133-2:2017+A1, IEC 62368- 1:2014, UN Manual Section 38.3, IC:32467-A2045, IEC60825-1-2007
Humidity	100% non-condensation	<b>₩ (€ F© </b>	
Ingress protection	IP68 <sup>(6)</sup> (according to IEC 60529)	(1) Compliant, but subject to availability of E service definition. GLONASS L3, Galileo E	BDS ICD, GLONASS, Galileo, QZSS and IRNSS commerci 6, Galileo E6 High Accuracy Service (HAS), BDS B2b an
0 1		SBAS L5 will be provided through future firm (2) Accuracy and reliability are determined	nware upgrade. under open sky, free of multipaths, optimal GNSS geomet assume minimum of 5 satellites, follow up of recommende
Drop	Survive a 2-meter pole-drop	and almospheric condition. Performances a	assume minimum of 5 satellites, follow up of recommende
	Survive a 2-meter pole-drop  Compliant with ISO 9022-36-08 and MIL-STD-810H	general GPS practices. PPP accuracy is sub precision static requires a minimum of 24 ho	pject to the region, environment, and convergence time. Hig ours of long-term observation and precise ephemeris.
Vibration  Waterproof and breathable	Compliant with ISO 9022-36-08 and	general GPS practices. PPP accuracy is sub precision static requires a minimum of 24 ho (3) CHCNAV's VPT™ (Virtual Pole Tip) te with the red point representing the staking of margins. (4) Compliant and 10 Hz to be provided throi (5) Typical observed values.	oject to the region, environment, and convergence time. Hig urus of long-term observation and precise ephemeris, schnology ensures precise alignment of the virtual pole to out location in the LandStar software within acceptable em ugh future firmware upgrade.
Vibration Waterproof and breathable membrane	Compliant with ISO 9022-36-08 and MIL-STD-810H  Prevent water vapor from entering	general GPS practices. PPP accuracy is sub- precision static requires a minimum of 24 ho (3) CHCNAV's VPT™ (Virtual Pole Tip) te with the red point representing the staking or margins. (4) Compliant and 10 Hz to be provided thro (5) Typical observed values. (6) Splash, water, and dust resistant and we of IP68 under IEC standard 60529. (7) Rechargeable and built-in 7.2 V / 490	oject to the region, environment, and convergence time. Hig urus of long-term observation and precise ephemeris, echnology ensures precise alignment of the virtual pole t out location in the LandStar software within acceptable err
Vibration  Waterproof and breathable membrane	Compliant with ISO 9022-36-08 and MIL-STD-810H  Prevent water vapor from entering under harsh environments.	general GPS practices. PPP accuracy is sub precision static requires a minimum of 24 ho (3) CHCNAV's VPT™ (Virtual Pole Tip) te with the red point representing the staking of margins. (4) Compliant and 10 Hz to be provided thror (5) Typical observed values. (6) Splash, water, and dust resistant and we of IP68 under IEC standard 60529. (7) Rechargeable and built-in 7.2 V / 490 temperature. (8) Avoid Direct Eye Contact with Beam	oject to the region, environment, and convergence time. Hig jurs of long-term observation and precise ephemeris, schnology ensures precise alignment of the virtual pole to out location in the LandStar software within acceptable err ugh future firmware upgrade. ere tested under controlled laboratory conditions with a ratir out mAh lithium battery. Battery life is subject to operatir
Vibration  Waterproof and breathable membrane  Ele  Power consumption	Compliant with ISO 9022-36-08 and MIL-STD-810H  Prevent water vapor from entering under harsh environments.	general GPS practices. PPP accuracy is sub precision static requires a minimum of 24 ho (3) CHCNAV's VPT™ (Virtual Pole Tip) te with the red point representing the staking of margins. (4) Compliant and 10 Hz to be provided thror (5) Typical observed values. (6) Splash, water, and dust resistant and we of IP68 under IEC standard 60529. (7) Rechargeable and built-in 7.2 V / 490 temperature. (8) Avoid Direct Eye Contact with Beam	oject to the region, environment, and convergence time. Hig urus of long-term observation and precise ephemeris, echnology ensures precise alignment of the virtual pole to out location in the LandStar software within acceptable err ugh future firmware upgrade. ere tested under controlled laboratory conditions with a ratif
Drop  Vibration  Waterproof and breathable membrane  Ele  Power consumption  Quick charge  Operating time on internal battery (7)	Compliant with ISO 9022-36-08 and MIL-STD-810H  Prevent water vapor from entering under harsh environments.  ectrical  Typical 2.0 W	general GPS practices. PPP accuracy is sub precision static requires a minimum of 24 ho (3) CHCNAV's VPT™ (Virtual Pole Tip) te with the red point representing the staking of margins. (4) Compliant and 10 Hz to be provided thro (5) Typical observed values. (6) Splash, water, and dust resistant and we of IP88 under IEC standard 60529. (7) Rechargeable and built-in 7.2 V / 490 temperature. (8) Avoid Direct Eye Contact with Beam (9) Adaptive frame rate, actual frame rate is a	oject to the region, environment, and convergence time. Hig jurs of long-term observation and precise ephemeris, schnology ensures precise alignment of the virtual pole to out location in the LandStar software within acceptable err ugh future firmware upgrade. ere tested under controlled laboratory conditions with a ratir out mAh lithium battery. Battery life is subject to operatir

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